

Tutorials 01

Exercise: Electrical Network Analysis with Linear Algebra and Probability

An electrical engineer analyzes a network with 3 buses (nodes) connected together. The voltages at the buses are given by the vector:

$$\mathbf{V} = \begin{bmatrix} V_1 \\ V_2 \\ V_3 \end{bmatrix}$$

where V_i is the voltage at bus i in volts. The network admittance matrix (relating currents and voltages) is:

$$\mathbf{Y} = \begin{bmatrix} 10 & -5 & -5 \\ -5 & 10 & -5 \\ -5 & -5 & 10 \end{bmatrix} \text{ S (siemens)}$$

1. Compute the current vector $\mathbf{I} = \mathbf{YV}$ for $\mathbf{V} = \begin{bmatrix} 230 \\ 220 \\ 210 \end{bmatrix}$ V.
2. Compute the 2-norm (Euclidean norm) of $\mathbf{V}$ and interpret its meaning.
3. Suppose V_1 is a random variable following a normal distribution $V_1 \sim \mathcal{N}(230, 4^2)$ V, $V_2 \sim \mathcal{N}(220, 5^2)$ V, and $V_3 \sim \mathcal{N}(210, 3^2)$ V.
 - a) Compute the expected value and variance of the current $I_1 = 10V_1 - 5V_2 - 5V_3$.
 - b) What is the probability that $I_1 > 15$ A?

Exercise: Predicting Power Loss in a Transmission Line

Problem Statement:

An engineer wants to estimate the **power loss** P_{loss} (in watts) in a transmission line as a function of the **line current** I (in amps) using a linear model: $P_{loss} = \theta_0 + \theta_1 I$

Given data (measured in the field):

Current I (A)	Power Loss P_{loss} (W)
10	120
20	190
30	250
40	310
50	380

Tasks:

1. Formulate the **linear regression cost function** for this dataset.
2. Compute the **optimal parameters** θ_0, θ_1 analytically using the **normal equation**.
3. Predict the power loss when $I = 35$ A.
4. Implement the regression using **Scikit-learn** in Python.

Exo 03 (devoir)

Consider a simple electrical circuit with three resistors in a mesh configuration, where the goal is to find the current in one branch. The circuit can be modeled by Kirchhoff's Voltage Law (KVL), leading to the matrix equation $\mathbf{A}\mathbf{I} = \mathbf{V}$, where:

- $\mathbf{I} = \begin{pmatrix} I_1 \\ I_2 \end{pmatrix}$ is the vector of mesh currents (in amperes, A).
- $\mathbf{V} = \begin{pmatrix} 10 \\ 0 \end{pmatrix}$ is the voltage source vector (in volts, V).
- The resistance matrix $\mathbf{A}$ is given by $\mathbf{A} = \begin{pmatrix} R_1 + R_2 & -R_2 \\ -R_2 & R_2 + R_3 \end{pmatrix}$, where R_1, R_2, R_3 are the resistances (in ohms, Ω).

Assume the resistors have nominal values but with tolerances: R_1 and R_3 are fixed at 5Ω each, while R_2 is a random variable uniformly distributed between 8Ω and 12Ω (due to manufacturing variation). This uniform distribution models uncertainty in component values, common in electrical engineering for reliability analysis in AI systems.

1. **Linear Algebra Part:** Solve for the current vector $\mathbf{I}$ in terms of R_2 (i.e., find I_1 and I_2 using matrix inversion or solving the system). Then, compute the L2 norm (Euclidean norm) of $\mathbf{I}$, which represents the root-mean-square (RMS) current magnitude, useful for power dissipation calculations: $\|\mathbf{I}\|_2 = \sqrt{I_1^2 + I_2^2}$.
2. **Probability Part:** Since $R_2 \sim \mathcal{U}(8, 12)$ (uniform distribution), find the expectation $\mathbb{E}[I_1]$ and variance $\text{Var}(I_1)$ of the current I_1 (the primary branch current). Recall that for a uniform random variable $X \sim \mathcal{U}(a, b)$, $\mathbb{E}[X] = \frac{a+b}{2}$ and $\text{Var}(X) = \frac{(b-a)^2}{12}$. However, since I_1 is a function of R_2 , you'll need to derive these from the expression for $I_1(R_2)$.

Exo 04

Physical context (DC motor)

In a DC motor, the electromagnetic torque T depends mainly on:

- $x_1 = I$: armature current (A)
- $x_2 = \omega$: angular speed (rad/s)

For a limited operating region, the torque can be approximated by a **linear model**:

$$T = \theta_0 + \theta_1 I + \theta_2 \omega$$

This type of approximation is widely used in:

- motor identification
- control design
- AI-based modeling of electromechanical systems

Experimental data

Measurements obtained from a DC motor test bench:

Test	Current I (A)	Speed ω (rad/s)	Torque T (N·m)
1	1	50	1.6
2	2	60	2.3
3	3	70	3.0
4	4	80	3.7

Questions

1. Write the regression model in **matrix form**
2. Estimate the parameters $\theta_0, \theta_1, \theta_2$ using the **normal equation**
3. Give the **identified motor torque model**
4. Predict the torque for:
 - $I = 5$ A
 - $\omega = 90$ rad/s
5. Implement the solution in **Python**