

FILIERE : Génie Civil

SPECIALITE : Master Géotechnique (M1/S1)

COURS : Mécanique des milieux continus

INTERROGATION N°1

(Date : 30/11/2025 – Durée : 1 heure 30)

Ex. 1 (12 points) Considérons les vecteurs $\bar{U} = {}^t\{5 \ 5 \ 0\}$ et $\bar{V} = {}^t\{5 \ -5 \ 0\}$ définis dans le repère orthonormé $(\bar{x}_1, \bar{x}_2, \bar{x}_3)$. On demande de calculer les opérations suivantes et de commenter éventuellement les résultats correspondants :

- Les normes $r_{\bar{U}}$ et $r_{\bar{V}}$
- Le produit scalaire $\bar{U} \cdot \bar{V}$
- Le produit vectoriel $\bar{W} = \bar{U} \wedge \bar{V}$
- Le produit mixte $(\bar{U}, \bar{V}, \bar{W})$
- Le produit tensoriel $\bar{T} = \bar{U} \otimes \bar{V}$
- Le déterminant du tenseur $\bar{T}$
- La trace du tenseur $\bar{T}$
- La transposée du tenseur $\bar{T}$
- La partie symétrique $\bar{T}_s$
- La partie antisymétrique $\bar{T}_a$

Ex. 2 (8 points) Soit le tenseur suivant :

$$\bar{M} = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 2 & 3 \\ 2 & 1 & -1 \end{pmatrix}$$

On demande de calculer :

- $Tr(\bar{M}) = M_{pp} = ?$
- $[Tr(\bar{M})]^2 = M_{pp}M_{qq} = ?$
- $Tr(\bar{M}^2) = M_{pq}M_{qp} = ?$
- $Tr(\bar{M} {}^t\bar{M}) = M_{pq}M_{pq} = ?$

N.B. : Seules les notes de cours sont autorisées. Ne pas oublier d'encadrer les résultats.

Bonne chance

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Corrigé

Exercice 1

Les vecteurs considérés sont :

$$\blacktriangleright \bar{U} = {}^t\{5 \quad 5 \quad 0\} = \begin{pmatrix} 5 \\ 5 \\ 0 \end{pmatrix} \quad / \quad (\bar{x}_1, \bar{x}_2, \bar{x}_3)$$

$$\blacktriangleright \bar{V} = {}^t\{5 \quad -5 \quad 0\} = \begin{pmatrix} 5 \\ -5 \\ 0 \end{pmatrix} \quad / \quad (\bar{x}_1, \bar{x}_2, \bar{x}_3)$$

• Normes :

Norme du vecteur $\bar{A}$: $r = \|\bar{A}\| = \sqrt{A_p A_p} \quad | \quad p = 1, 2, 3$

$$\Rightarrow r_{\bar{U}} = \|\bar{U}\| = \sqrt{U_1^2 + U_2^2 + U_3^2} = \sqrt{5^2 + 5^2 + 0^2} = 5\sqrt{2} \quad \#1$$

$$\Rightarrow r_{\bar{V}} = \|\bar{V}\| = \sqrt{V_1^2 + V_2^2 + V_3^2} = \sqrt{5^2 + (-5)^2 + 0^2} = 5\sqrt{2} \quad \#1$$

Remarque :

$$r_{\bar{U}} = r_{\bar{V}} = 5\sqrt{2} \quad \Rightarrow \quad \text{Les deux vecteurs sont orthogonaux et de même longueur.}$$

• Produit scalaire : $\bar{U} \cdot \bar{V}$

$$\bar{U} \cdot \bar{V} = U_p V_p \quad \Rightarrow \quad \bar{U} \cdot \bar{V} = U_1 V_1 + U_2 V_2 + U_3 V_3 = 5 \times 5 + 5 \times (-5) + 0 \times 0 = 0 \quad \#1$$

Vérification 1 :

$$\bar{U} \cdot \bar{V} = \frac{1}{4}(\|\bar{U} + \bar{V}\|^2 - \|\bar{U} - \bar{V}\|^2) \quad | \quad \bar{U} + \bar{V} = {}^t\{10 \quad 0 \quad 0\} \quad \text{et} \quad \bar{U} - \bar{V} = {}^t\{0 \quad 10 \quad 0\}$$

$$\Rightarrow \bar{U} \cdot \bar{V} = \frac{1}{4} \times \left[(\sqrt{10^2 + 0^2 + 0^2})^2 - (\sqrt{0^2 + 10^2 + 0^2})^2 \right] = \frac{1}{4}(100 - 100) = 0 \quad \text{Ok.}$$

Vérification 2 :

$$\bar{U} \cdot \bar{V} = \|\bar{U}\| \times \|\bar{V}\| \times \cos(\alpha) \quad | \quad \alpha = \text{Angle}(\bar{U}, \bar{V}) \quad \& \quad \bar{U} \perp \bar{V} \quad \Rightarrow \quad \alpha = \pi/2$$

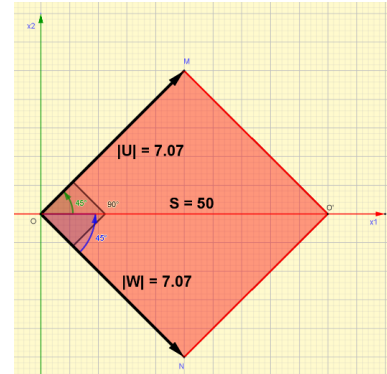
$$\Rightarrow \cos(\alpha) = \frac{\bar{U} \cdot \bar{V}}{\|\bar{U}\| \times \|\bar{V}\|} = \frac{0}{5\sqrt{2} \times 5\sqrt{2}} = 0 \quad \Rightarrow \quad \alpha = \pi/2 \quad \text{Ok.}$$

• Produit vectoriel : $\bar{W} = \bar{U} \wedge \bar{V}$

$$\bar{W} = \bar{U} \wedge \bar{V} = \begin{vmatrix} \bar{x}_1 & \bar{x}_2 & \bar{x}_3 \\ U_1 & U_2 & U_3 \\ V_1 & V_2 & V_3 \end{vmatrix} = \begin{pmatrix} W_1 \\ W_2 \\ W_3 \end{pmatrix} = {}^t\{W_1 \quad W_2 \quad W_3\} \quad / \quad (\bar{x}_1, \bar{x}_2, \bar{x}_3)$$

$$\begin{aligned} \Rightarrow \bar{W} = \bar{U} \wedge \bar{V} &= \begin{vmatrix} \bar{x}_1 & \bar{x}_2 & \bar{x}_3 \\ 5 & 5 & 0 \\ 5 & -5 & 0 \end{vmatrix} = \begin{vmatrix} 5 & 0 \\ -5 & 0 \end{vmatrix} \bar{x}_1 - \begin{vmatrix} 5 & 0 \\ 5 & 0 \end{vmatrix} \bar{x}_2 + \begin{vmatrix} 5 & 5 \\ 5 & -5 \end{vmatrix} \bar{x}_3 \\ &= 0\bar{x}_1 + 0\bar{x}_2 - 50\bar{x}_3 \end{aligned}$$

$$\Rightarrow \bar{W} = \begin{pmatrix} 0 \\ 0 \\ -50 \end{pmatrix} = {}^t\{0 \quad 0 \quad -50\} / (\bar{x}_1, \bar{x}_2, \bar{x}_3) \quad \#1$$



Vérification :

$$\bar{W} = \bar{U} \wedge \bar{V}$$

$$\Rightarrow W_i = \epsilon_{ijk} U_j V_k \quad | \quad \epsilon_{ijk} = \begin{cases} +1 & \text{si permutation paire : } 1, 2, 3 / 2, 3, 1 / 3, 1, 2 \\ -1 & \text{si permutation impaire : } 1, 3, 2 / 2, 1, 3 / 3, 2, 1 \end{cases}$$

$$\Rightarrow \begin{cases} W_1 = \epsilon_{123} U_2 V_3 + \epsilon_{132} U_3 V_2 = +1 \times 5 \times 0 - 1 \times 0 \times (-5) = 0 \\ W_2 = \epsilon_{231} U_3 V_1 + \epsilon_{213} U_1 V_3 = +1 \times 0 \times 5 - 1 \times 5 \times 0 = 0 \\ W_3 = \epsilon_{312} U_1 V_2 + \epsilon_{321} U_2 V_1 = +1 \times 5 \times (-5) - 1 \times 5 \times 5 = -50 \end{cases}$$

Ok.

Symbole de permutation
 $\epsilon_{123} = \epsilon_{231} = \epsilon_{312} = +1$
 $\epsilon_{132} = \epsilon_{213} = \epsilon_{321} = -1$

• **Produit mixte : $(\bar{U}, \bar{V}, \bar{W})$**

$$(\bar{U}, \bar{V}, \bar{W}) = \begin{vmatrix} U_1 & U_2 & U_3 \\ V_1 & V_2 & V_3 \\ W_1 & W_2 & W_3 \end{vmatrix}$$

$$\begin{aligned} \Rightarrow (\bar{U}, \bar{V}, \bar{W}) &= \begin{vmatrix} 5 & 5 & 0 \\ 5 & -5 & 0 \\ 0 & 0 & -50 \end{vmatrix} \\ &= 5 \times \begin{vmatrix} -5 & 0 \\ 0 & -50 \end{vmatrix} - 5 \times \begin{vmatrix} 5 & 0 \\ 0 & -50 \end{vmatrix} + 0 \times \begin{vmatrix} 5 & -5 \\ 0 & 0 \end{vmatrix} \\ &= 5 \times (-5) \times (-50) - 5 \times 5 \times (-50) + 0 \\ &= 2500 \quad \text{\#1} \end{aligned}$$

Vérification : $V = |(\bar{U}, \bar{V}, \bar{W})| = S \times h$

$$h = |W_3| = 50$$

$$S = \|\bar{V}\| \times \|\bar{W}\| \times \sin(\alpha) = 5\sqrt{2} \times 5\sqrt{2} \times \sin\left(\frac{\pi}{2}\right) = 50$$

$$\Rightarrow V = 50 \times 50 = 2500 \quad \text{Ok.}$$

• **Produit tensoriel : $\bar{T} = \bar{U} \otimes \bar{V}$**

$$\bar{T} = \bar{U} \otimes \bar{V} \quad \Rightarrow \quad \bar{T} = [t_{ij}] = [U_i V_j] = \begin{bmatrix} U_1 V_1 & U_1 V_2 & U_1 V_3 \\ U_2 V_1 & U_2 V_2 & U_2 V_3 \\ U_3 V_1 & U_3 V_2 & U_3 V_3 \end{bmatrix}$$

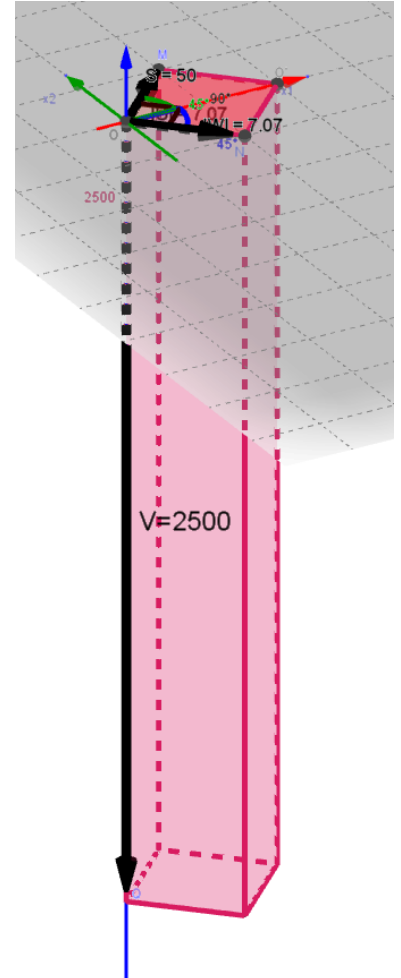
$$\begin{aligned} \Rightarrow \bar{T} &= \begin{bmatrix} 5 \times 5 & 5 \times (-5) & 5 \times 0 \\ 5 \times 5 & 5 \times (-5) & 5 \times 0 \\ 0 \times 5 & 0 \times (-5) & 0 \times 0 \end{bmatrix} \\ &= 25 \times \begin{bmatrix} 1 & -1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{\#1} \end{aligned}$$

• **Trace du tenseur $\bar{T}$**

$$Tr(\bar{T}) = t_{ij} \quad \Rightarrow \quad t_{ii} = t_{11} + t_{22} + t_{33}$$

$$\Rightarrow t_{ii} = 25 \times (1 - 1 + 0) = 0 \quad \text{\#1}$$

$$\Rightarrow \text{C'est un tenseur déviatorique} \quad \text{\#1}$$



• Déterminant du tenseur $\bar{\bar{T}}$

$$\det(\bar{\bar{T}}) = |t_{ij}| = \begin{vmatrix} t_{11} & t_{12} & t_{13} \\ t_{21} & t_{22} & t_{23} \\ t_{31} & t_{32} & t_{33} \end{vmatrix}$$

$$\Rightarrow \det(\bar{\bar{T}}) = 25 \times \begin{vmatrix} 1 & -1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 0 \end{vmatrix} = 25 \times \left[1 \times \begin{vmatrix} -1 & 0 \\ 0 & 0 \end{vmatrix} - (-1) \times \begin{vmatrix} 1 & 0 \\ 0 & 0 \end{vmatrix} + 0 \times \begin{vmatrix} 1 & -1 \\ 0 & 0 \end{vmatrix} \right] = 0 \quad \#1$$

Vérification :

$$\det(\bar{\bar{T}}) = \frac{1}{6} \epsilon_{ijk} \epsilon_{pqr} t_{ip} t_{jq} t_{kr}$$

$$\Rightarrow \det(\bar{\bar{T}}) = \frac{1}{6} \begin{pmatrix} \epsilon_{123} \epsilon_{123} t_{11} t_{22} t_{33} + \epsilon_{123} \epsilon_{231} t_{12} t_{23} t_{31} + \epsilon_{123} \epsilon_{312} t_{13} t_{21} t_{32} \\ + \\ \epsilon_{123} \epsilon_{132} t_{11} t_{23} t_{32} + \epsilon_{123} \epsilon_{213} t_{12} t_{21} t_{33} + \epsilon_{123} \epsilon_{321} t_{13} t_{22} t_{31} \\ + \\ \epsilon_{231} \epsilon_{123} t_{21} t_{32} t_{13} + \epsilon_{231} \epsilon_{231} t_{22} t_{33} t_{11} + \epsilon_{231} \epsilon_{312} t_{23} t_{31} t_{12} \\ + \\ \epsilon_{231} \epsilon_{132} t_{21} t_{33} t_{12} + \epsilon_{231} \epsilon_{213} t_{22} t_{31} t_{13} + \epsilon_{231} \epsilon_{321} t_{23} t_{32} t_{11} \\ + \\ \epsilon_{312} \epsilon_{123} t_{31} t_{12} t_{23} + \epsilon_{312} \epsilon_{231} t_{32} t_{13} t_{21} + \epsilon_{312} \epsilon_{312} t_{33} t_{11} t_{22} \\ + \\ \epsilon_{312} \epsilon_{132} t_{31} t_{13} t_{22} + \epsilon_{312} \epsilon_{213} t_{32} t_{11} t_{23} + \epsilon_{312} \epsilon_{321} t_{33} t_{12} t_{21} \\ + \\ \epsilon_{132} \epsilon_{123} t_{11} t_{32} t_{23} + \epsilon_{132} \epsilon_{231} t_{12} t_{33} t_{21} + \epsilon_{132} \epsilon_{312} t_{13} t_{31} t_{22} \\ + \\ \epsilon_{132} \epsilon_{132} t_{11} t_{33} t_{22} + \epsilon_{132} \epsilon_{213} t_{12} t_{31} t_{23} + \epsilon_{132} \epsilon_{321} t_{13} t_{32} t_{21} \\ + \\ \epsilon_{213} \epsilon_{123} t_{21} t_{12} t_{33} + \epsilon_{213} \epsilon_{231} t_{22} t_{13} t_{31} + \epsilon_{213} \epsilon_{312} t_{23} t_{11} t_{32} \\ + \\ \epsilon_{213} \epsilon_{132} t_{21} t_{13} t_{32} + \epsilon_{213} \epsilon_{213} t_{22} t_{11} t_{33} + \epsilon_{213} \epsilon_{321} t_{23} t_{12} t_{31} \\ + \\ \epsilon_{321} \epsilon_{123} t_{31} t_{22} t_{13} + \epsilon_{321} \epsilon_{231} t_{32} t_{23} t_{11} + \epsilon_{321} \epsilon_{312} t_{33} t_{21} t_{12} \\ + \\ \epsilon_{321} \epsilon_{132} t_{31} t_{23} t_{12} + \epsilon_{321} \epsilon_{213} t_{32} t_{21} t_{13} + \epsilon_{321} \epsilon_{321} t_{33} t_{22} t_{11} \end{pmatrix}$$

$$\Rightarrow \det(\bar{\bar{T}}) = \frac{25}{6} \begin{pmatrix} (+1) \times (+1) \times 1 \times (-1) \times 0 + (+1) \times (+1) \times (-1) \times 0 \times 0 + (+1) \times (+1) \times 0 \times 1 \times 0 \\ + \\ (+1) \times (-1) \times 1 \times 0 \times 0 + (+1) \times (-1) \times (-1) \times 1 \times 0 + (+1) \times (-1) \times 0 \times (-1) \times 0 \\ + \\ (+1) \times (+1) \times 1 \times 0 \times 0 + (+1) \times (+1) \times (-1) \times 0 \times 1 + (+1) \times (+1) \times 0 \times 0 \times (-1) \\ + \\ (+1) \times (-1) \times 1 \times 0 \times (-1) + (+1) \times (-1) \times (-1) \times 0 \times 0 + (+1) \times (-1) \times 0 \times 0 \times 1 \\ + \\ (+1) \times (+1) \times 0 \times (-1) \times 0 + (+1) \times 0 \times 0 \times 0 \times 1 + (+1) \times (+1) \times 0 \times 1 \times (-1) \\ + \\ (+1) \times (-1) \times 0 \times 0 \times (-1) + (+1) \times (-1) \times 0 \times 1 \times 0 + (+1) \times (-1) \times 0 \times (-1) \times 1 \\ + \\ (-1) \times (+1) \times 1 \times 0 \times 0 + (-1) \times (+1) \times (-1) \times 0 \times 1 + (-1) \times (+1) \times 0 \times 0 \times (-1) \\ + \\ (-1) \times (-1) \times 1 \times 0 \times (-1) + (-1) \times (-1) \times (-1) \times 0 \times 0 + (-1) \times (-1) \times 0 \times 0 \times 1 \\ + \\ (-1) \times (+1) \times 1 \times (-1) \times 0 + (-1) \times (+1) \times (-1) \times 0 \times 0 + (-1) \times (+1) \times 0 \times 1 \times 0 \\ + \\ (-1) \times (+1) \times 1 \times 0 \times 0 + (-1) \times (+1) \times (-1) \times 1 \times 0 + (-1) \times (+1) \times 0 \times (-1) \times 0 \\ + \\ (-1) \times (+1) \times 0 \times (-1) \times 0 + (-1) \times (-1) \times 0 \times 0 \times 1 + (-1) \times (-1) \times 0 \times 1 \times (-1) \\ + \\ (-1) \times (-1) \times 0 \times 0 \times (-1) + (-1) \times (-1) \times 0 \times 1 \times 0 + (-1) \times (-1) \times 0 \times (-1) \times 1 \end{pmatrix}$$

$$\Rightarrow \det(\bar{\bar{T}}) = 0 \quad Ok.$$

- Transposée du tenseur $\bar{\bar{T}}$

$$\begin{aligned}\bar{\bar{T}} = [t_{ij}] &\Rightarrow {}^t\bar{\bar{T}} = [t_{ji}] \\ \Rightarrow \bar{\bar{T}} = [t_{ij}] &= 25 \times \begin{pmatrix} 1 & -1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow {}^t\bar{\bar{T}} = [t_{ji}] = 25 \times \begin{pmatrix} 1 & 1 & 0 \\ -1 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \#1\end{aligned}$$

- Partie symétrique $\bar{\bar{T}}_s$ du tenseur $\bar{\bar{T}}$

$$\begin{aligned}\bar{\bar{T}}_s &= \frac{1}{2}(\bar{\bar{T}} + {}^t\bar{\bar{T}}) \Rightarrow (t_s)_{ij} = \frac{1}{2}(t_{ij} + t_{ji}) \\ \Rightarrow \bar{\bar{T}}_s &= \frac{25}{2} \times \left[\begin{pmatrix} 1 & -1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} + \begin{pmatrix} 1 & 1 & 0 \\ -1 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right] = 25 \times \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \#1\end{aligned}$$

- Partie antisymétrique $\bar{\bar{T}}_a$ du tenseur $\bar{\bar{T}}$

$$\begin{aligned}\bar{\bar{T}}_a &= \frac{1}{2}(\bar{\bar{T}} - {}^t\bar{\bar{T}}) \Rightarrow (t_a)_{ij} = \frac{1}{2}(t_{ij} - t_{ji}) \\ \Rightarrow \bar{\bar{T}}_a &= \frac{25}{2} \times \left[\begin{pmatrix} 1 & -1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} - \begin{pmatrix} 1 & 1 & 0 \\ -1 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right] = 25 \times \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \#1\end{aligned}$$

Exercice 2

- $Tr(\bar{\bar{M}}) = M_{pp}$

$$\Rightarrow Tr(\bar{\bar{M}}) = M_{pp} = M_{11} + M_{22} + M_{33} = 1 + 2 - 1 = 2 \quad \#2$$

- $[Tr(\bar{\bar{M}})]^2 = M_{pp}M_{qq}$

$$\Rightarrow [Tr(\bar{\bar{M}})]^2 = M_{pp}M_{qq} = (M_{11} + M_{22} + M_{33})(M_{11} + M_{22} + M_{33})$$

$$\Rightarrow [Tr(\bar{\bar{M}})]^2 = (1 + 2 - 1) \times (1 + 2 - 1) = 2 \times 2 = 4 \quad \#2$$

Vérification :

$$Tr(\bar{\bar{M}}) = 2 \Rightarrow [Tr(\bar{\bar{M}})]^2 = 2^2 = 4 \quad Ok.$$

- $Tr(\bar{\bar{M}}^2) = M_{pq}M_{qp}$

$$\Rightarrow Tr(\bar{\bar{M}}^2) = M_{pq}M_{qp} = M_{11}^2 + M_{22}^2 + M_{33}^2 + 2(M_{12}M_{21} + M_{23}M_{32} + M_{13}M_{31})$$

$$\Rightarrow Tr(\bar{\bar{M}}^2) = M_{pq}M_{qp} = 1^2 + 2^2 + (-1)^2 + 2 \times [0 \times (-1) + 3 \times 1 + 0 \times 2] = 12 \quad \#2$$

Vérification :

$$\bar{\bar{M}} = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 2 & 3 \\ 2 & 1 & -1 \end{pmatrix} \Rightarrow \bar{\bar{M}}^2 = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 2 & 3 \\ 2 & 1 & -1 \end{pmatrix} \times \begin{pmatrix} 1 & 0 & 0 \\ -1 & 2 & 3 \\ 2 & 1 & -1 \end{pmatrix}$$

$$\Rightarrow \bar{\bar{M}}^2 = \begin{pmatrix} 1 \times 1 + 0 \times (-1) + 0 \times 2 & 1 \times 0 + 0 \times 2 + 0 \times 1 & 1 \times 0 + 0 \times 3 + 0 \times (-1) \\ (-1) \times 1 + 2 \times (-1) + 3 \times 2 & (-1) \times 0 + 2 \times 2 + 3 \times 1 & (-1) \times 0 + 2 \times 3 + 3 \times (-1) \\ 2 \times 1 + 1 \times (-1) + (-1) \times 2 & 2 \times 0 + 1 \times 2 + (-1) \times 1 & 2 \times 0 + 1 \times 3 + (-1) \times (-1) \end{pmatrix}$$

$$\Rightarrow \bar{\bar{M}}^2 = \begin{pmatrix} 1 & 0 & 0 \\ 3 & 7 & 3 \\ -1 & 1 & 4 \end{pmatrix} \Rightarrow Tr(\bar{\bar{M}}^2) = (\bar{\bar{M}}^2)_{ii} = 1 + 7 + 4 = 12 \quad Ok$$

$$\bullet Tr(\bar{\bar{M}} {}^t\bar{\bar{M}}) = M_{pq}M_{pq} = Tr({}^t\bar{\bar{M}}\bar{\bar{M}})$$

$$\Rightarrow Tr(\bar{\bar{M}} {}^t\bar{\bar{M}}) = M_{pq}M_{pq} = M_{11}M_{11} + M_{12}M_{12} + M_{13}M_{13} + M_{21}M_{21} + M_{22}M_{22} + M_{23}M_{23} + \\ + M_{31}M_{31} + M_{32}M_{32} + M_{33}M_{33}$$

$$\Rightarrow Tr(\bar{\bar{M}} {}^t\bar{\bar{M}}) = M_{pq}M_{pq} = 1 \times 1 + 0 \times 0 + 0 \times 0 + (-1) \times (-1) + 2 \times 2 + 3 \times 3 + \\ + 2 \times 2 + 1 \times 1 + (-1) \times (-1) = 21 \quad \#2$$

Vérification :

$$\bar{\bar{M}} = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 2 & 3 \\ 2 & 1 & -1 \end{pmatrix} \Rightarrow {}^t\bar{\bar{M}} = \begin{pmatrix} 1 & -1 & 2 \\ 0 & 2 & 1 \\ 0 & 3 & -1 \end{pmatrix}$$

$$\Rightarrow \bar{\bar{M}} {}^t\bar{\bar{M}} = \begin{pmatrix} 1 \times 1 + 0 \times 0 + 0 \times 0 & 1 \times (-1) + 0 \times 2 + 0 \times 3 & 1 \times 2 + 0 \times 1 + 0 \times (-1) \\ (-1) \times 1 + 2 \times 0 + 3 \times 0 & (-1) \times (-1) + 2 \times 2 + 3 \times 3 & (-1) \times 2 + 2 \times 1 + 3 \times (-1) \\ 2 \times 1 + 1 \times 0 + (-1) \times 0 & 2 \times (-1) + 1 \times 2 + (-1) \times 3 & 2 \times 2 + 1 \times 1 + (-1) \times (-1) \end{pmatrix}$$

$$\Rightarrow \bar{\bar{M}} {}^t\bar{\bar{M}} = \begin{pmatrix} 1 & -1 & 2 \\ -1 & 14 & -3 \\ 2 & -3 & 6 \end{pmatrix}$$

$$\Rightarrow Tr(\bar{\bar{M}} {}^t\bar{\bar{M}}) = (\bar{\bar{M}} {}^t\bar{\bar{M}})_{ii} = 1 + 14 + 6 = 21 \quad Ok$$