

Mohamed Boudiaf
University
-M'sila-



Faculty of Mathematics
and Computer Science



Computer Science
Department

OPERATING SYSTEMS II

CHAPTER II PROCESS SYNCHRONIZATION

EVENTS AND LOCKS

3rd Year, Computer Science - SI

Dr. Hanene CHERAIT

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PROCESS SYNCHRONIZATION TECHNIQUES

SYNCHRONIZATION

- ◉ The solutions proposed for the mutual exclusion problem cannot be used when it comes to more complex problems.
- ◉ In these problems, the focus is on **synchronization** in its broadest sense.
- ◉ A process acts on one or more other processes through **blocking and unblocking**.
- ◉ **Synchronization tools** aim to control competition and the evolution of processes.
- ◉ They are also involved in implementing **cooperation** in general.
- ◉ **Cooperation = Communication + Synchronization**

SYNCHRONISATION

Events

Locks

Semaphores

Monitors

Critical Sections

Path Expressions

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EVENTS

- Processes that are **blocked** after requesting access to their critical sections to use a shared resource **R** wait for the occurrence of an **event**, which in this case is the **release of the resource R**.
- An event is represented by a **Boolean variable**, initialized to **false**:
 - False**: R is busy (occupied)
 - True**: R is free (available)

EVENTS

- Two primitives are used by processes to handle the event:
 - wait(event):** the calling process is blocked only when the *event* has not been signaled.
 - signal(event):** wakes up the blocked process(es) and sets the variable *event* to *true*.

event R_free = false // Resource is busy

Process A:

wait(R_free)

use_resource()

signal(R_free)

Process B:

wait(R_free)

use_resource()

signal(R_free)

Only one process at a time accesses the resource; others wait for the **signal** indicating it's free again.

TYPES OF EVENTS

⊙ Manual-reset event

- Once signaled, it stays *true* until it's **manually reset** to *false*.
- Multiple waiting processes can be released.
 - *Used when several processes must respond to the same signal.*

⊙ Auto-reset event

- Automatically returns to *false* after releasing **one** waiting process.
 - Useful when only one process should proceed after a signal.

ADVANTAGES OF EVENTS

◉ Avoids Active Waiting (CPU-Efficient)

- processes can **wait passively** for an event to occur instead of continuously checking a condition (busy waiting).
- This saves CPU time and power, improving system efficiency.

◉ Asynchronous Communication

- Allow processes to **communicate asynchronously** – one thread signals when a condition is met, while others respond when notified.
- This decouples their execution and improves responsiveness.

◉ Suitable for I/O Operations

- Ideal for situations where a process must wait for I/O completion, device input, or network responses without blocking the entire system.

◉ Efficient Task Coordination

- Events can be used to notify when tasks finish, resources become available, or new data is ready
 - enabling smooth coordination between processes.

◉ Better Resource Utilization

- Since processes sleep while waiting for events, system resources are used only when necessary.

DISADVANTAGES OF EVENTS

◉ Possible Missed Signals

- If a signal is sent **before** another thread starts waiting, the event may be **lost**,
 - if a thread starts waiting **after** the event was signaled, it won't know that the event already occurred.
 - causing the waiting thread to stay **blocked forever**.

◉ Timing Sensitivity

- Correct behavior often depends on precise timing (who waits first, who signals first)
 - making programs **non-deterministic** and hard to debug.

◉ Complex Dependency Management

- In systems with multiple interdependent events, coordinating the order and logic between them becomes difficult and error-prone.

DISADVANTAGES OF EVENTS

◉ Limited Functionality

- Unlike other synchronization mechanisms, events can't handle **counting**, **ownership**, or **resource tracking** directly.

◉ Difficult Error Handling

- If an event is missed or triggered incorrectly, there's no built-in mechanism to recover or detect that failure.

◉ Potential Deadlocks or Starvation

- Poor event handling logic can cause processes to wait indefinitely for signals that never arrive.

◉ Debugging Challenges

- Because event-triggered execution is asynchronous, tracing program flow and identifying timing bugs can be very difficult.

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- ⦿ This lock-based synchronization solution is designed to avoid **busy waiting** at the processor level.
- ⦿ It assigns to the **critical resource (CR)** a waiting queue “**Q(CR)**”, which is used to store the processes that are unable to access their **critical sections (CS)**.
- ⦿ A Boolean variable called “**lock**” is also used to manage process access to critical resources.

LOCKS

Common context: lock: boolean; // initialized to false

Entry primitive (lock);

Begin

 If (not lock) then
 lock := true;

 Else

 enqueue(Q(CR)); /* block and add the process to the waiting queue */

End;

Exit primitive (lock);

Begin

 If (not empty(Q(CR))) then
 remove(Pj); /* remove a process from the waiting queue */

 Else

 lock := false;

End;

LOCKS

Process P_i ;

Begin

Repeat

...

Entry(lock); // entry protocol

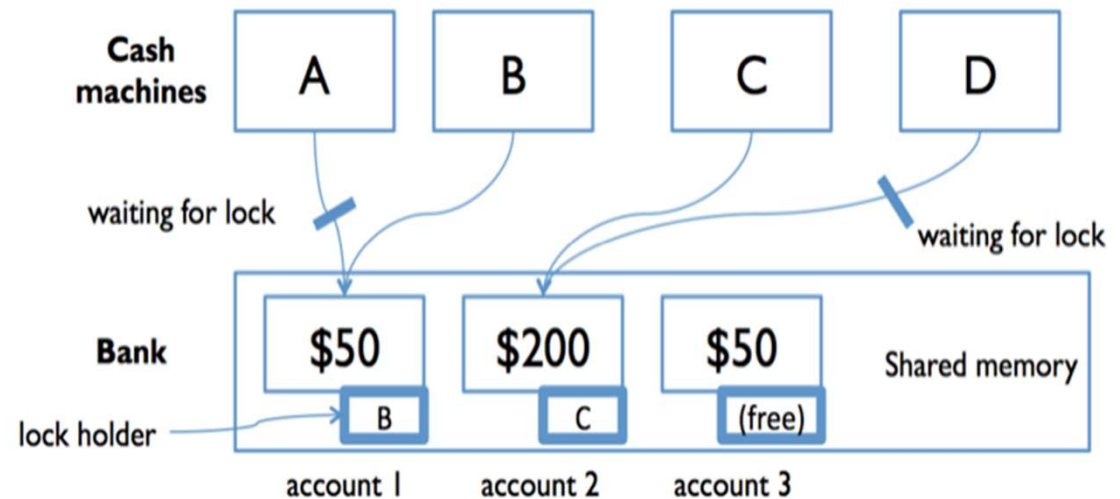
CRITICAL SECTION;

Exit(lock); // exit protocol

...

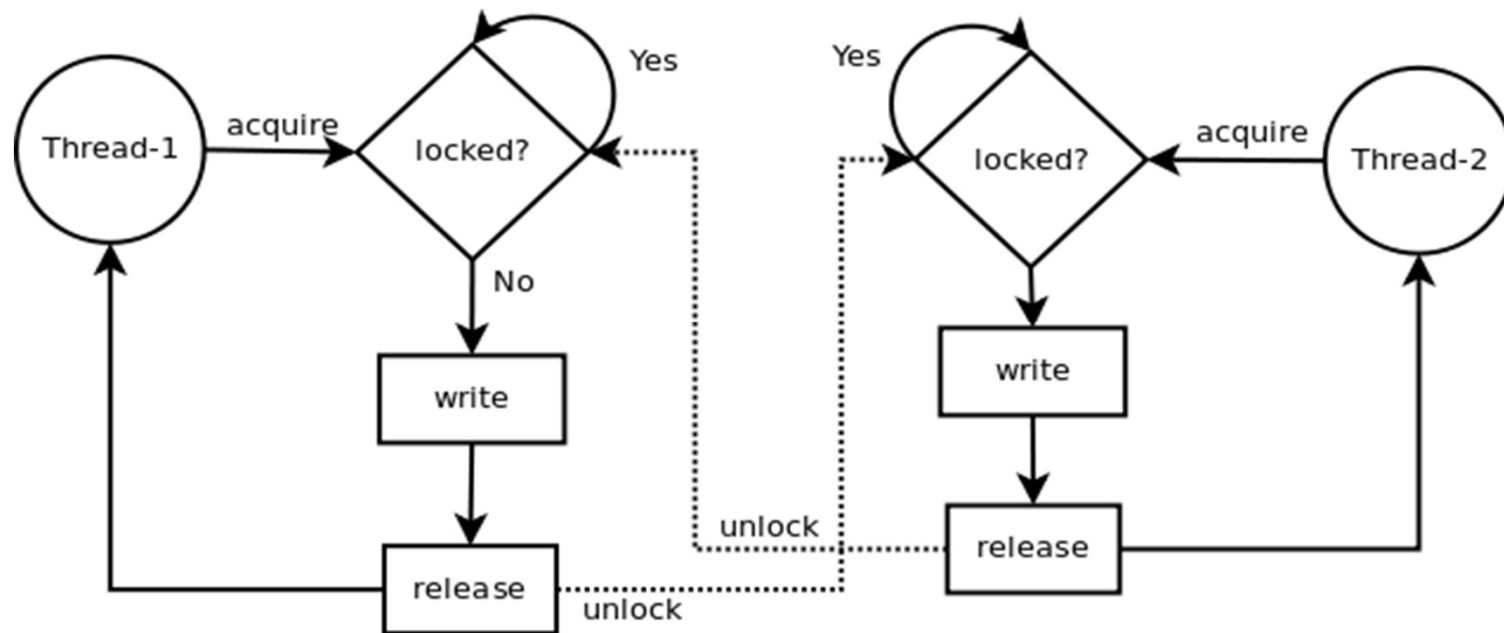
Until false;

End;

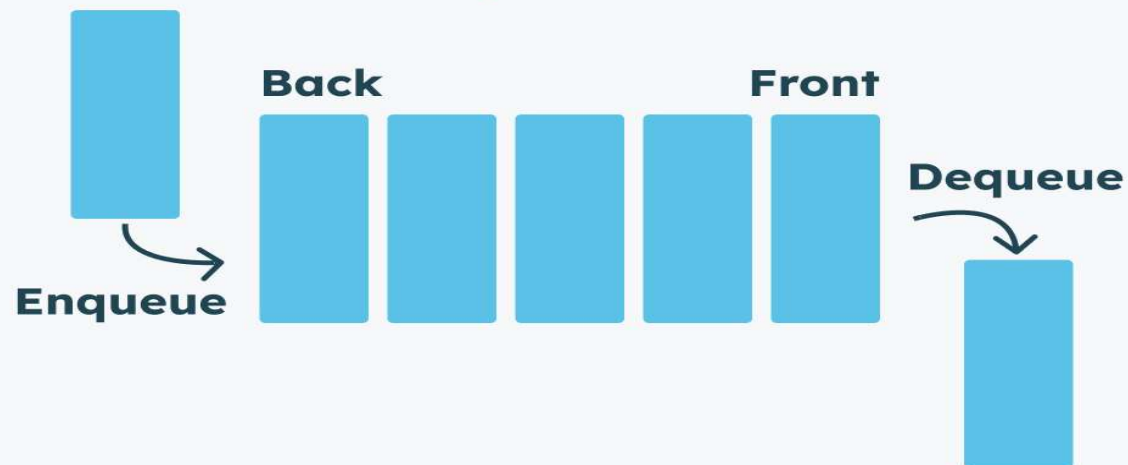


On many machines, locks are handled directly by two **indivisible primitives**, “**Lock(lock)**” and “**unLock(lock)**”, which respectively simulate the behavior of the two primitives “**Entry(lock)**” and “**Exit(lock)**”.

LOCKS



How queues work



ADVANTAGES OF LOCKS

- ◉ **Avoid busy waiting**

- Processes that cannot acquire the lock are **blocked** and **removed from the CPU**, saving CPU cycles.

- ◉ **Efficient CPU utilization**

- Other processes can continue executing while blocked processes wait for the lock.

- ◉ **Mutual exclusion**

- Guarantees that only one process enters the critical section at a time.

- ◉ **Fairness possible**

- With a queue (like **Q(R)**), processes can be served in **FIFO order**, reducing starvation.

- ◉ **Deterministic behavior**

- Provides predictable access to shared resources when correctly implemented.

DISADVANTAGES OF LOCKS

◉ Resource underutilization

- Simple locks do not handle **multiple copies** of a resource efficiently — some resources may remain **idle** while processes wait.
 - Ex: A database server might allow **N simultaneous connections**.

◉ Deadlock risk

- If multiple locks are acquired in the wrong order, processes can wait indefinitely for each other.

◉ Priority inversion

- A low-priority process holding a lock can block a higher-priority process, delaying time-critical tasks.

◉ Context-switch overhead

- Blocking and waking up processes requires OS intervention, which adds overhead.

◉ Implementation complexity

- Fairness, queues, and multi-resource management make locks more complex to implement correctly.

THANK YOU FOR YOUR
ATTENTION

