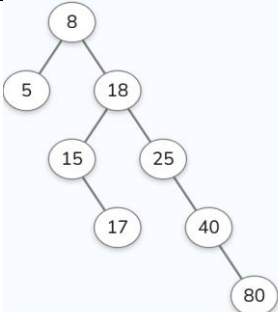
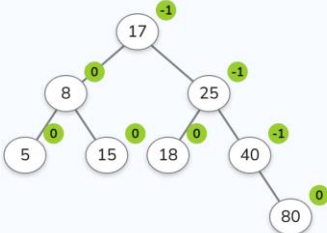
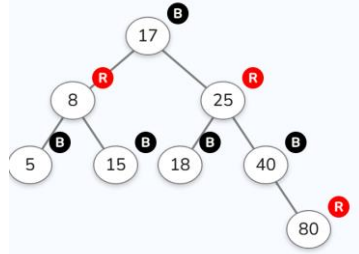


Exam Correction

Exercise 1

a) insert [8, 18, 5, 15, 17, 25, 40, 80]

BST (0.5pts)	AVL (1pts)	RB TREE (1pts)
		

b) Indicate the correct answer(s) for each of the following questions:

Q1) Why might open addressing be preferred over chaining in certain systems?

(0.5pts)

- B. It improves cache locality due to contiguous memory storage
- C. It avoids pointer overhead associated with linked structures

Q2) Which factors explain why tabulation is often preferred over memoization in practice?

(0.5pts)

- A. It avoids recursion overhead and stack overflow risks
- C. It enables predictable memory access patterns favorable to CPU caches

Q3) Why is studying NP-complete problems fundamental in computer science? (0.5pts)

- A. It helps identify problems unlikely to have efficient exact solutions
- C. It guides the use of approximation algorithms and heuristics

Q4) A large NP-complete problem is solved using dynamic programming with frequent state lookups. Which design choices are most justified? (0.5pts)

- A. Tabulation to eliminate recursion overhead
- C. Open addressing to improve cache efficiency

5) Which statements about NP-complete problems are correct?

(0.5pts)

- A. A polynomial-time solution to one NP-complete problem implies $P = NP$
- C. NP-complete problems are in NP

Exercise 2 (5pts)

```
def minimumTotal(triangle):
    memo = {}
    def dfs(row, col):
        # Base case: reached the bottom row
        if row == len(triangle) - 1: return triangle[row][col]

        if (row, col) in memo: return memo[(row, col)]
        min_path = triangle[row][col] + min(
            dfs(row + 1, col),    # Move to same index
            dfs(row + 1, col + 1) # Move to next index
        )

        memo[(row, col)] = min_path
        return min_path

    return dfs(0, 0)
```

Exercise 3(5pts)

```
def boundaryOfBinaryTree(root):
    if not root: return []
    result = [root.val]
    getLeftBoundary(root.left, result)
    getLeaves(root, result)
    getRightBoundary(root.right, result)
    return result

def getLeftBoundary(node, result):
    if not node: return
    if node.left or node.right:
        result.append(node.val)

    if node.left:
        getLeftBoundary(node.left, result)
    else:
        getLeftBoundary(node.right, result)
```

```
def getRightBoundary(node, result):
    if not node: return
    if node.right:
        getRightBoundary(node.right, result)
    else:
        getRightBoundary(node.left, result)
    if node.left or node.right:
        result.append(node.val)

def getLeaves(node, result):
    if not node: return
    if not node.left and not node.right:
        result.append(node.val)
        return
    getLeaves(node.left, result)
    getLeaves(node.right, result)
```

Exercise 4 (5pts)

def countCompleteConnectedComponents(n, edges):

```
# Build adjacency list
adj = [ [] for _ in range(n)]
for u, v in edges:
    adj[u].append(v)
    adj[v].append(u)

visited = set()
complete_count = 0

def dfs(node, component):
    visited.add(node)
    component.append(node)

# Recursively visit all unvisited neighbors
    for neighbor in adj[node]:
        if neighbor not in visited:
            dfs(neighbor, component)
# Find all connected components
for i in range(n):
    if i not in visited:
        component = []
        dfs(i, component)
        # Check if this component is complete
        # A complete graph with k vertices has k*(k-1)/2 edges
        k = len(component)
        required_edges = k * (k - 1) // 2
        # Count actual edges in this component
        actual_edges = 0
        for node in component:
            actual_edges += len(adj[node])
        # Each edge is counted twice (once from each endpoint)
        actual_edges //= 2

        if actual_edges == required_edges:
            complete_count += 1

return complete_count
```