

Graphs Theory

Basics (1)



University of M'sila
Faculty of Mathematics and informatics
Mathematics department

Specialty:
Applied Mathematics

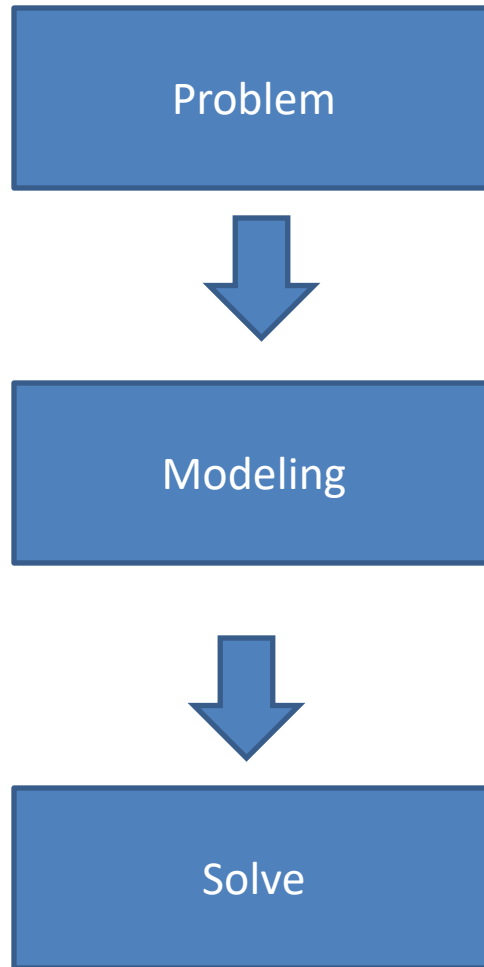
L3
2024/2025

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Plan

- ❑ Introduction
- ❑ Definition of graph
- ❑ Order, size, and degree
- ❑ Successor and predecessor
- ❑ Type of graph
- ❑ Path, chain, cycle, and circuit
- ❑ Eulerian graph
- ❑ Hamiltonian graph
- ❑ Connectivity

Introduction (**motivation**)



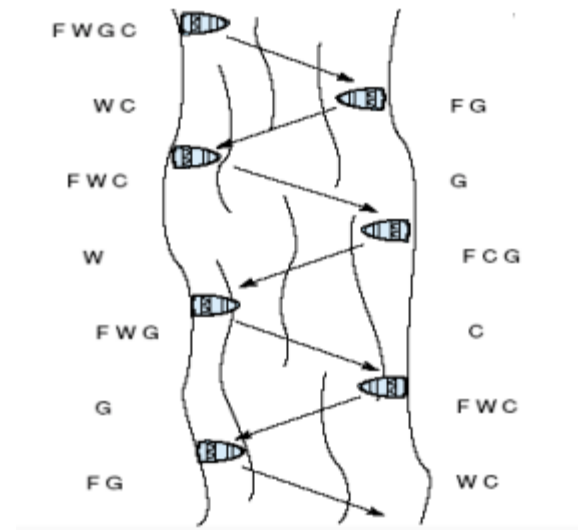
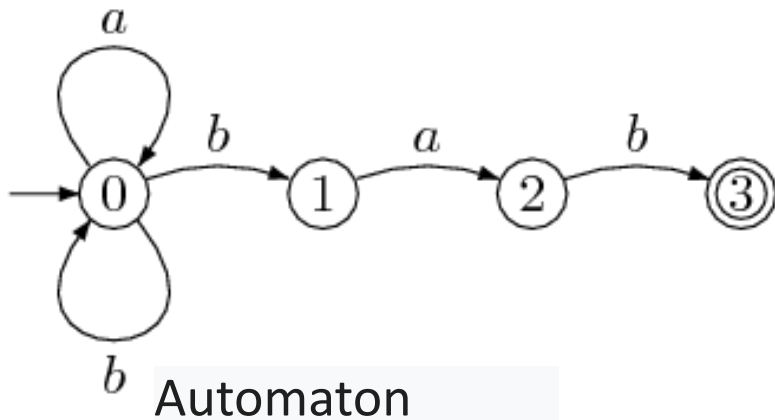
Introduction (motivation)



Road networks



Pipeline process



Definition of graph

- A **graph** $G=(V, E)$ is a pair where :
 - V is a set of **vertices** (or points or nodes)
 - E is a set of **edges**(or lines)
 - Each edge or lines has (joins) two **incident** ends.
 - These two incident ends are called **adjacent** (neighbors) vertices.
 - If $e=(u,v)$; we say that the vertex u and the edge e are incident with each other.
 - If two edges are incident with a common vertex then they are called **adjacent** lines.
 - A graph with p vertices and q edges is called a **(p, q) graph**.
 - Edge joining vertex to itself is called a **loop**

Definition of graph

Example: for the following graph

$$V=\{1,2,3,4,5,6,7\}$$

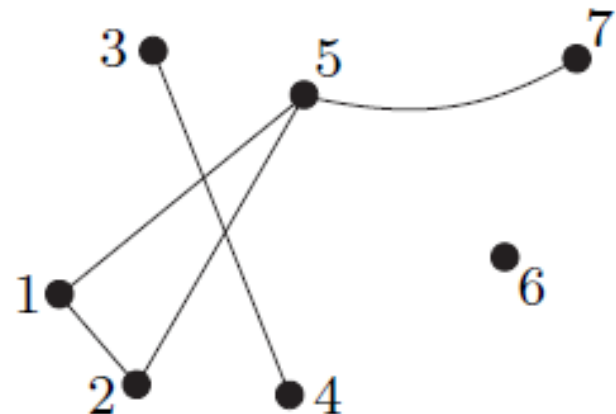
$$E=\{(1,2), (1,5), (2,5), (3,4), (5,7),\}$$

The vertices 1 and 2 are adjacent

We observe that:

$$E \subseteq V^2$$

$$E \cap V = \emptyset$$



V11

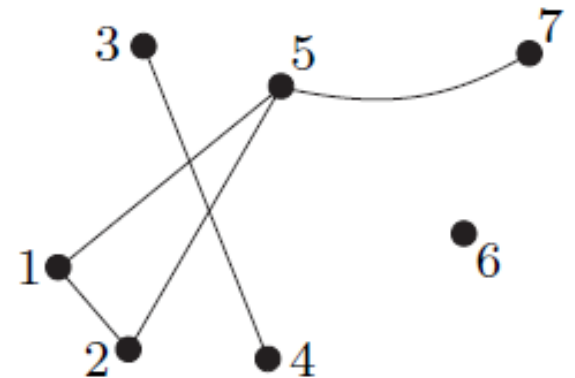
Definition of graph

The line (1,2) and the vertex 1 are incident with each other.

the lines (1,5), (2,5), are adjacent.

This graph is a (7,5) graph.

▪ Non adjacent vertices or edges are called **independent**



Order, size and Degree

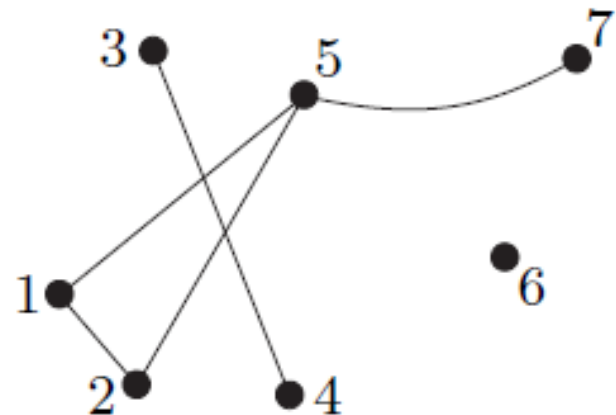
□ The **order** of a graph is its number of vertices, denoted by $|V|$

□ The **size** of a graph is its number of edges, denoted by $|E|$

Example:

$$n = |V| = 7$$

$$m = |E| = 5$$



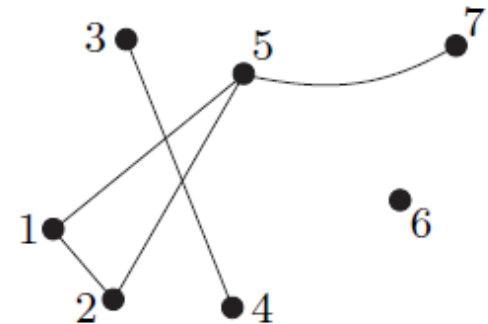
Order, size and Degree

- Let $G=(V,E)$ is a non empty graph
- We denote by $N_G(v)$ the set of Neighbors of a vertex v .
- We denote by $d_G(v)$, or simply $d(v)$ the set of neighbors of a vertex v .
- If $d(v) = 0$ the
Vertex v is **isolated** .

$$d(1)=2$$

$$d(6)=0$$

Note: Loops are counted twice.



Order, size and Degree

□ We denote by $\delta(G) = \min\{d(v) | v \in V\}$

The minimum **degree** of G .

□ We denote by $\Delta(G) = \max\{d(v) | v \in V\}$

The maximum degree of G .

□ The average degree of G : $\bar{d}(G) = \frac{1}{|V|} \sum_{v \in V} d(v)$

$$\delta(G) \leq \bar{d}(G) \leq \Delta(G)$$

Order, size and Degree

$$|E| = \frac{1}{2} \sum_{v \in V} d(v) = \frac{1}{2} d(G) \cdot |V|$$

□ Proposition : the number of vertices of odd degree in a graph is always even

Note : in the case of the oriented graph we split $d(v)$

$d^{\text{in}}_+(v)$: Number of edges having v as initial-endpoint
 $d^-(v)$: Number of edges having v as terminal endpoint

$$d(v) = d^+_+(v) + d^-(v)$$

Order, size and Degree

□ If all the vertices of a graph G have the same degree K then G called **K -regular** or simply regular.

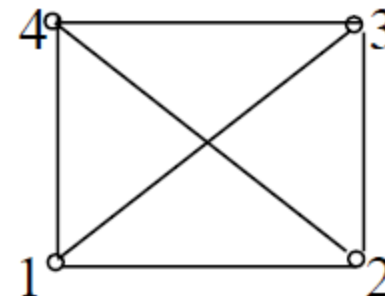
A **3-regular** graph is called **cubic**

In a regular graph always we have :

$$\delta(G) = \Delta(G)$$

Example:

$$\delta(G) = \Delta(G) = 3$$



Theorem : Every cubic graph has an even number of points.

Set of successors, predecessors

□ We denote by :

- $\Gamma^+(v)$: set of **successor** of vertex v
- $\Gamma^-(v)$: set of **predecessor** of vertex v
- $\Gamma(v) = \Gamma^-(v) \cup \Gamma^+(v)$

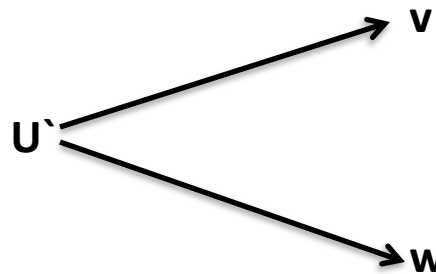
Example:

v is a successor of u

u is a predecessor of v

$$\Gamma^+(u) = \{v, w\}$$

$$\Gamma^-(v) = \{u\}$$



Set of successors, predecessors

□if

- $\Gamma^+(v) = \phi$ then: v is a **sink** vertex
- $\Gamma^-(v) = \phi$ then: v is a **source** vertex
- $\Gamma(v) = \phi$ then : v is an **isolated** vertex

Graph

Directed Vs undirected

Oriented	Non oriented
Edge	Line
Path	chain
Loop	Loop
Circuit	Cycle

Types of graphs

□ **Valuated graph** : Let $G(V,E)$ be a graph (directed or undirected) we define an application

$$f : E \rightarrow \mathbb{R}$$

□ f is called valuation of the graph G .

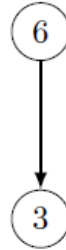
$$\forall (u, v) \in V^2 : (u, v) = +\infty$$

if $(u, v) \notin E$

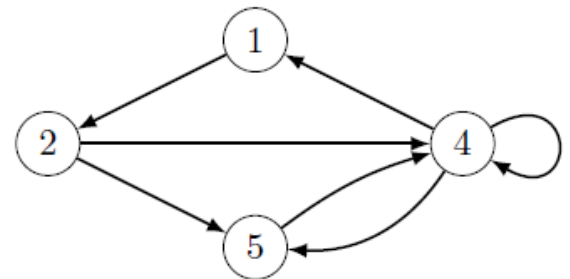
Types of graphs

❑ Simple : Let $G(V,E)$ be a graph, G is **a simple graph** if no loops and each pair of vertices are joined at most by one edge.

$$\forall (u, v) \in V^2 \exists \text{at most } (u, v) \in E$$



❑ Otherwise G is called **multi-graph**.



Types of graphs

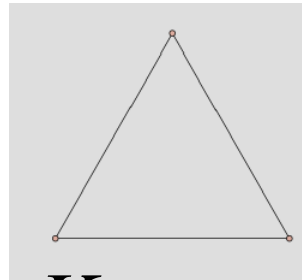
□ Complete graph : Let $G(V,E)$ is a simple graph, G is **complete** iff

$$\forall (u,v) \in V^2 : (u,v) \in E$$

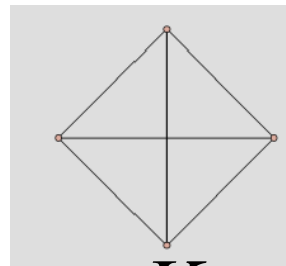
□ A complete graph with p vertices is denoted by

$$K_p$$

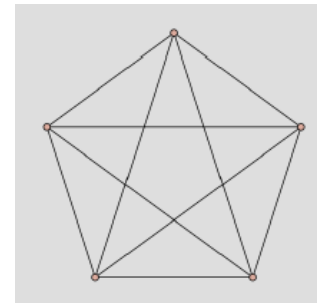
□ Example:



K_3



K_4

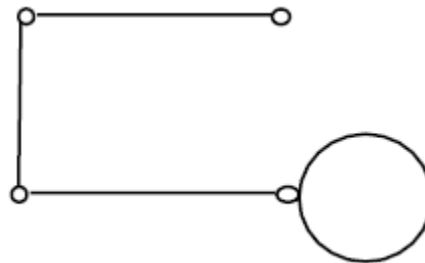


K_5

Types of graphs

❑ If a vertex has multiple lines and loops then the graph is called **PSEUDO GRAPH**

❑ Example:

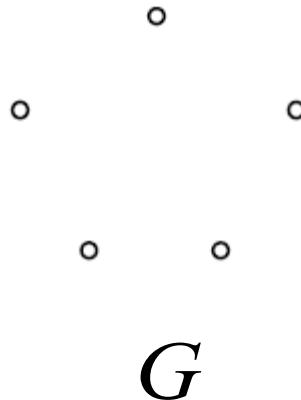


Types of graphs

□ Null graph : Let $G(V,E)$ is a graph, G is a **null graph** iff:

$$E = \phi$$

□ Example:



Types of graphs

□ **BIPARTITE GRAPH** : Let $G(V,E)$ is a graph, G is called a ***bigraph or bipartite graph*** if the vertex set V can be partitioned into two disjoint subsets V_1 and V_2 such that every line of G joins a point of V_1 to a point of V_2 . (V_1, V_2) is called a bipartition of G .

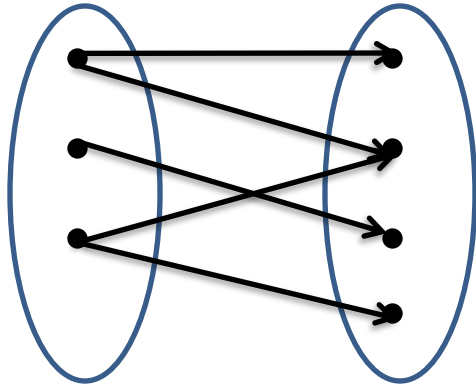
□ **Formaly** $V_1 \cap V_2 = \phi$ and $V_1 \cup V_2 = V$

□ **If** $(u, v) \in E$ and if $u \in V_1 \Rightarrow v \in V_2$

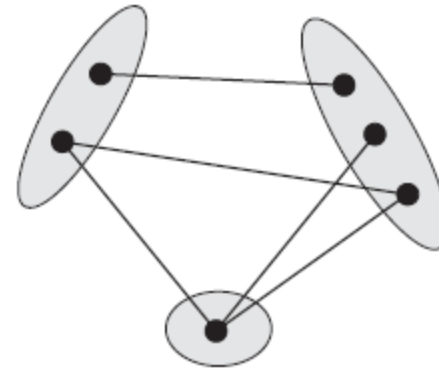
and vice versa

□ **Example:**

Types of graphs



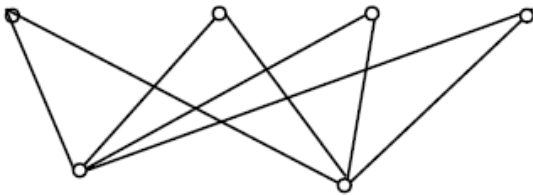
2-partite graph
Or simply bipartite graph



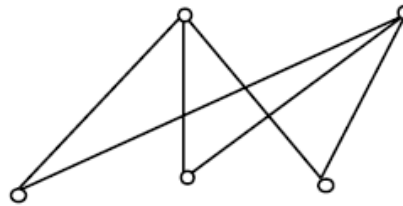
3-partite graph

Types of graphs

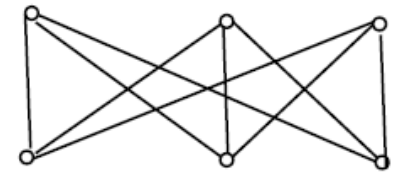
$K_{4,2}$



$K_{2,3}$



$K_{3,3}$



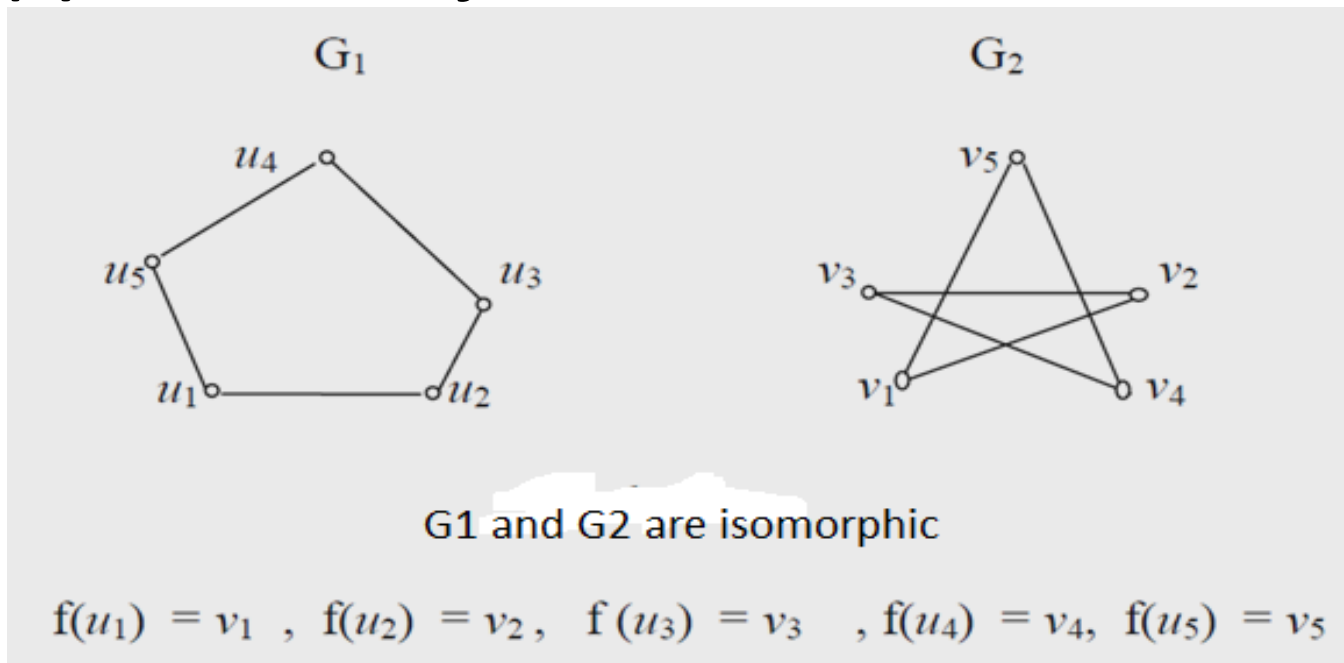
Complete bipartite graph

Proposition : a graph is a bipartite iff it contains no odd cycle

Types of graphs

□ ISOMORPHISM

Definition: Two graphs $G_1 = (V_1, X_1)$ and $G_2 = (V_2, X_2)$ are said to be **isomorphic** if there exists a bijection $f: V_1 \rightarrow V_2$ such that $u, v \in V_1$ are adjacent in G_1 iff $f(u), f(v) \in V_2$ are adjacent in G_2 .

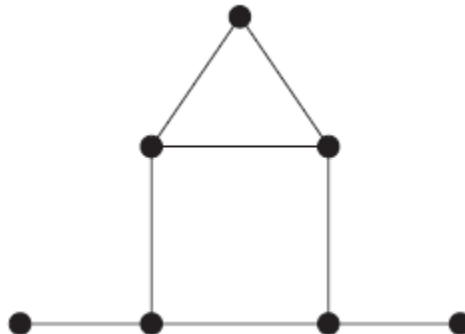


Types of graphs

❑ **Crossing number** of a graph G is the **minimum number** of pair wise intersections of the edges when G is drawn in the plane.

❑ A **planar graph** is called **outer planar if it can be embedded** in the plane so that all its vertices lie on the same face.

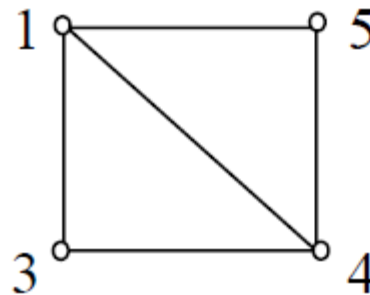
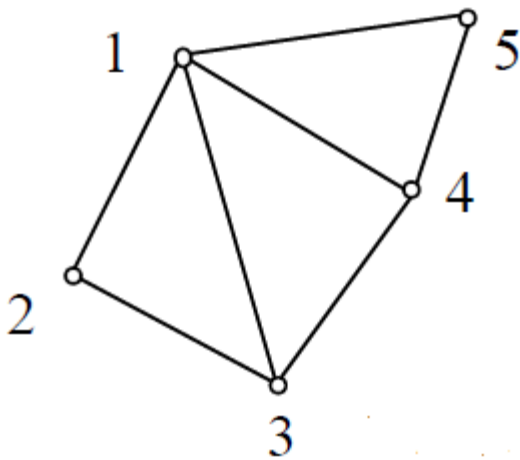
❑ Note: The crossing number of a planar graph is zero.



Types of graphs

□ Sub graph

Definition: A graph $H = (V_1, X_1)$ is called a **sub graph** of $G (V, X)$ if $V_1 \subseteq V$ and $X_1 \subseteq X$.

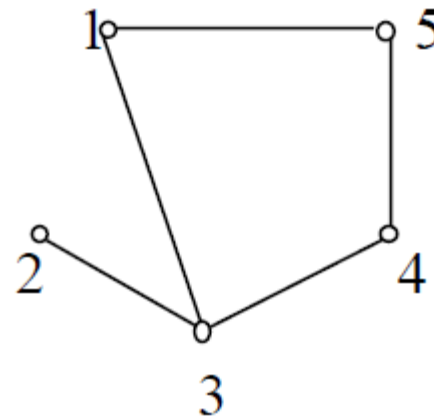
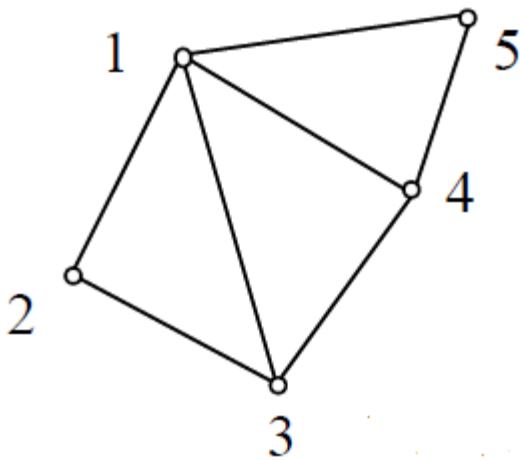


Types of graphs

□ PARTIAL GRAPH

Definition: Let Two graphs $G_1 = (V_1, X_1)$ and $G_2 = (V_2, X_2)$, G_2 is a **partial graph** of G_1

If $V_1 = V_2$, and $E_2 \subset E_1$



Types of graphs

□ REMOVAL OF A POINT :

▪ **Definition:** Let $G = (V, X)$ be a graph and $v \in V$. The subgraph of G obtained by removing the point v and all the lines incident with v is called the subgraph obtained by the removal of the point v and is denoted by $G - v$.

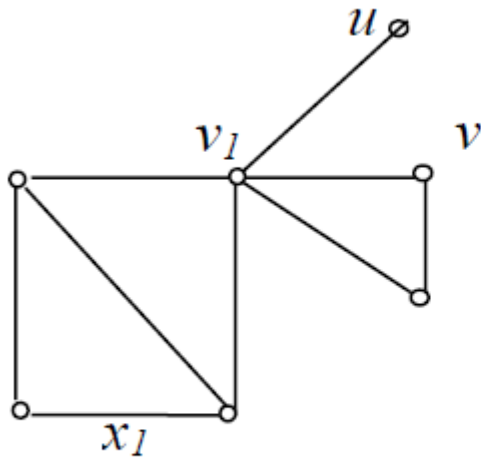
($G - v$ is an *induced subgraph* of G .)

□ REMOVAL OF A LINE

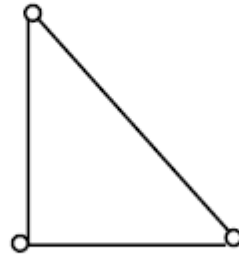
▪ **Definition:** Let $G = (V, X)$ be a graph and $x \in X$. Then $G - x = (V, X - \{x\})$ is called the *spanning subgraph* of G obtained by the removal of the line x .

($G - x$ is a spanning subgraph of G .)

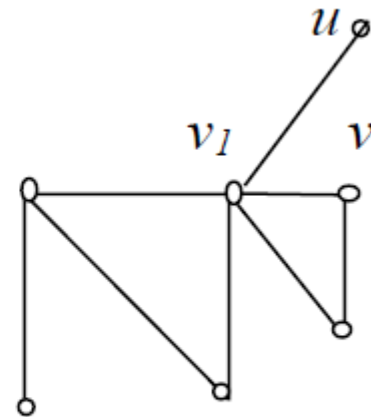
Types of graphs



G



$G - v_1$



$G - x_1$

Path, chain, circuit, cycle

□ Oriented graph

Definition: Let $G = (V, E)$ is an oriented graph

A path from vertex u to vertex v is a sequence

$\langle s_0, s_1, \dots, s_k \rangle$ where

$s_0 = u$ and $s_k = v$ and $(s_i, s_{i+1}) \in E \ \forall i \in \{0, 1, \dots, k-1\}$

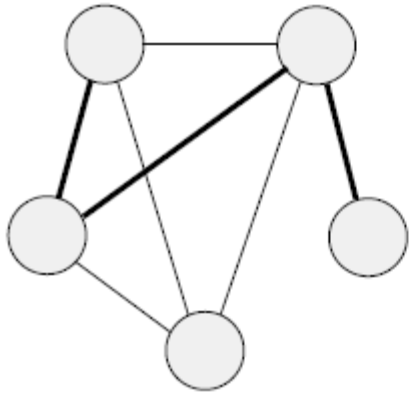
We can express this path either by:

$\langle s_0, s_1, \dots, s_k \rangle$ or by $\langle (s_0, s_1), \dots, (s_{k-1}, s_k) \rangle$

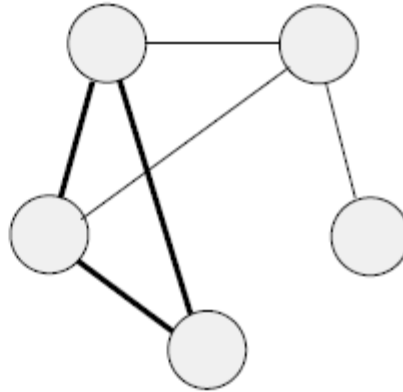
The length of this path is the number of edges that contains

Path, chain, circuit, cycle

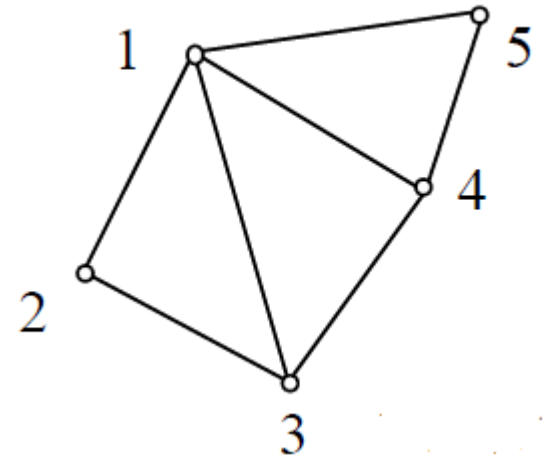
- ❑ Simple path: a path where all the edges that contains are different
- ❑ Elementary path: a path where all the vertices that contains are different.
- ❑ A path $\langle s_0, s_1, \dots, s_k \rangle$ is a circuit if $s_0 = s_k$ and if $k \geq 1$, where k is the number of edges.
- ❑ This circuit is simple if all the edges that contains are different.
- ❑ This circuit is elementary if $s_1, \dots, s_k$ are all distinct.
- ❑ A loop is a circuit whose length 1.



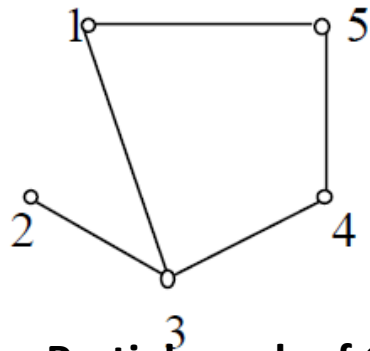
Path in connected graph



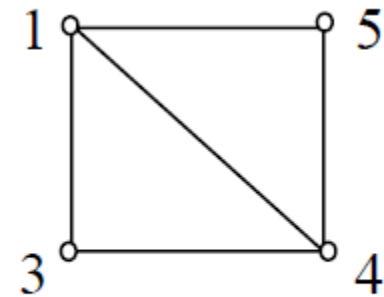
Cycle in connected graph



G1

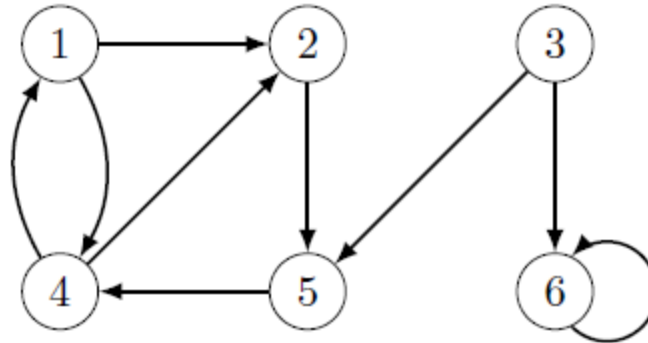


Partial graph of G1



Sub graph of G1

Path, chain, circuit, cycle



Elementary path is $\langle 2, 5, 4, 1 \rangle$.

no elementary path is $\langle 2, 5, 4, 1, 4 \rangle$..

elementary circuit is $\langle 1; 2; 5; 4; 1 \rangle$.

no elementary circuit $\langle 1; 2; 5; 4; 2; 5; 4; 1 \rangle$.

Simple path is $\langle 1, 2, 5, 4 \rangle$

No Simple path is $\langle 1, 2, 5, 4, 1, 2 \rangle$

Simple circuit is $\langle 1, 2, 5, 4, 1 \rangle$

No simple circuit is $\langle 1, 2, 5, 4, 1, 4, 1 \rangle$

Path, chain, circuit, cycle

□ In the case of no oriented graph we talk **chain** rather than **path**, **cycle** rather than **circuit**.

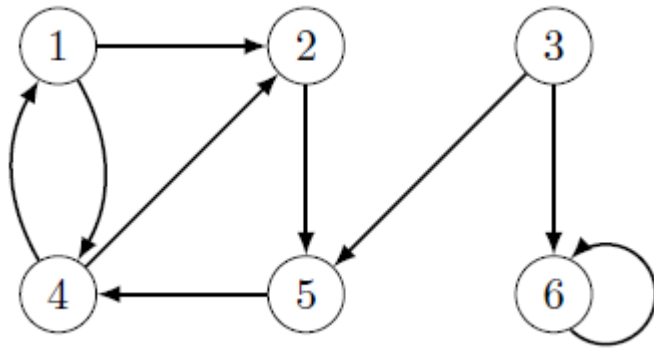
□ **Theorem(cycle)** : If G is a graph in which the degree of every vertex is at least two then G contains a cycle.

Path, chain, circuit, cycle

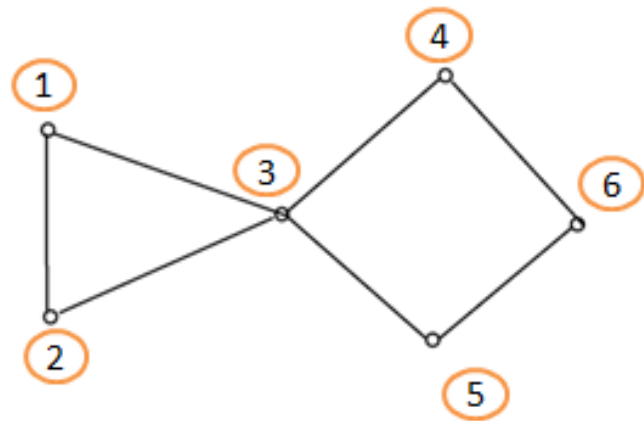
- ❑ **Hamiltonian path**: elementary path containing all the vertices of the graph.
- ❑ **Eulerian path**: simple path containing all the edges of the graph.
- ❑ **Hamiltonian graph**: graph containing an Hamiltonian cycle.
- ❑ **Semi Hamiltonian graph**: graph containing an Hamiltonian chain.
- ❑ **Eulerian graph**: graph containing an Eulerian cycle.
- ❑ **Semi Eulerian graph**: graph containing an Eulerian chain.

Path, chain, circuit, cycle

Example:



No Hamiltonian path
No Eulerian path



Hamiltonian path $\langle 1, 2, 3, 4, 6, 5 \rangle$
Eulerian cycle $\langle 1, 3, 5, 6, 4, 3, 2, 1 \rangle$

Eulerian graph

□ Theorem (cycle) : A connected graph is Eulerian if and only if every vertex has even degree.

□ Theorem(chain): A connected simple graph is semi-Eulerian iff It has 0 or exactly 2 vertices have an odd degree

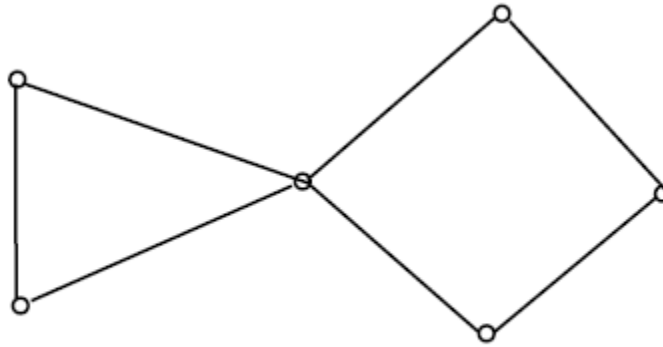
□ Theorem(Eulerian circuit): An oriented multigraph strongly connected contains an eulerian circuit iff: $d^+(s) = d^-(s) \forall s \in V$

□ Theorem(Eulerian path) : An oriented and connected multigraph contains an Eulerian path from the vertex u to the vertex v iff:

$$d^+(u) = d^-(u) + 1 \quad d^+(v) = d^-(v) - 1 \quad d^+(s) = d^-(s) \forall s \neq u, v$$

Eulerian graph

Example:



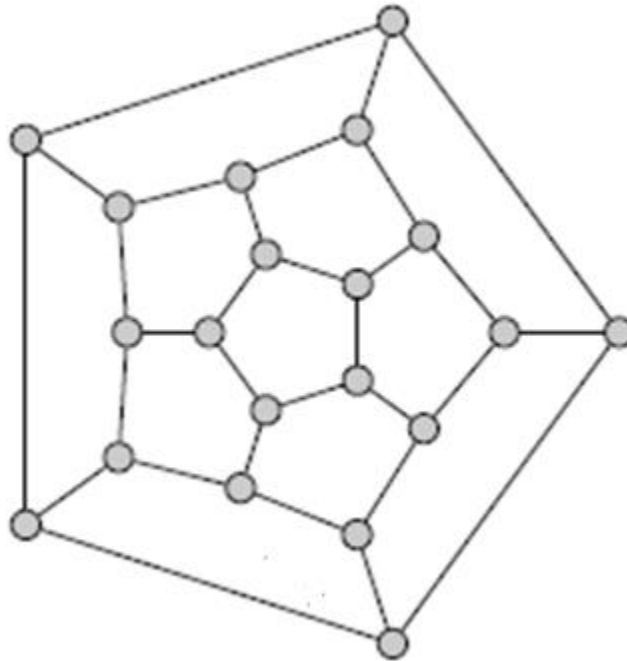
Hamiltonian graph

□ Simple sufficient conditions:

- A graph with vertex of degree 1 not Hamiltonian
- If a vertex in a graph has degree 2, then the two edges hold to Hamiltonian cycle.
- The K_n graphs are Hamiltonians.
- **Theorem (Ore):** Let G be a simple graph with p vertices, $p \geq 3$, if for all non adjacent two vertices u and v such that $d(u) + d(v) \geq p$. Then G is Hamiltonian.
- **Theorem (Dirac):**
 - If G is a graph with $p \geq 3$ vertices and $\delta \geq p / 2$ then G is Hamiltonian.

Hamiltonian graph

□ Example:



Connectivity

□ A non empty graph G is **connected** if :

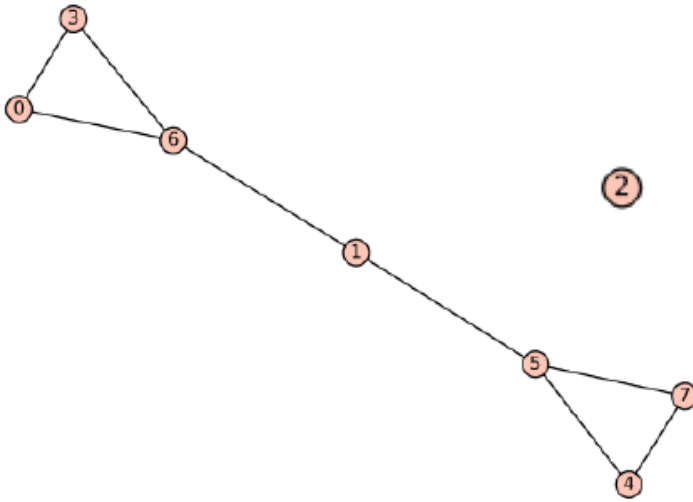
$\forall u, v \in V \Rightarrow \exists$ chain from u to v

□ A non empty graph G is **strongly connected** if :

$\forall u, v \in V \Rightarrow \exists$ path from u to v

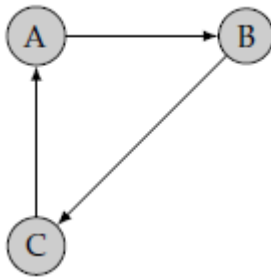
and $\exists$ path from v to u

Connectivity

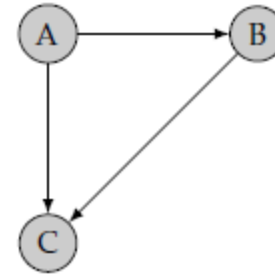


Disconnected graph
But it contains two connected
component(sub graphs)

Connectivity



Strongly connected graph



Simply connected graph

Simply connected component

Simply connected component research Algorithm

Let $G=(V,E)$ be a graph, $s \in V$

$SCC(s)=\phi$;

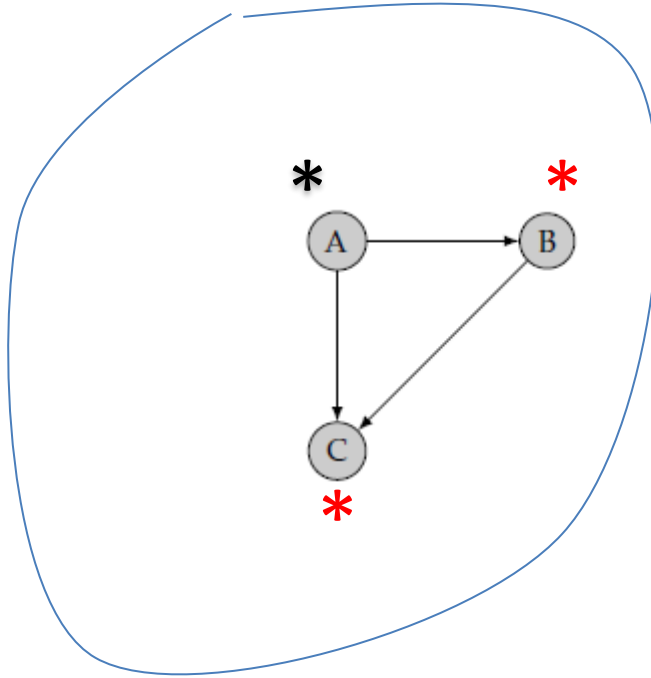
1-Put (*) on the vertex s ;

2-Put (*) on all adjacent vertices of a marked vertex;

3-repeat 2 until no mark is possible;

4-all the vertices **having** * mark construct a **SCC(s)**

Simply connected component



Strongly connected component

Strongly Connected Component Research Algorithm

Let $G=(V,E)$ be a graph, $s \in V$

$StCC(s)=\phi$;

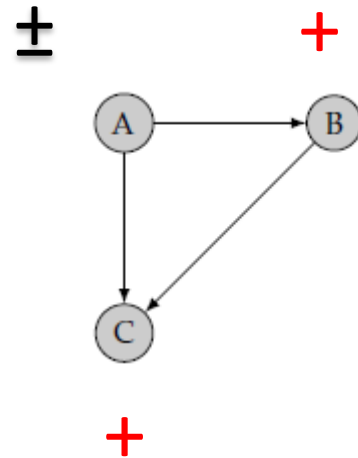
1-Put $(\pm)$ on the vertex s ;

2-Put $(+)$ on all successors not yet marked of all vertices marked by $(+)$

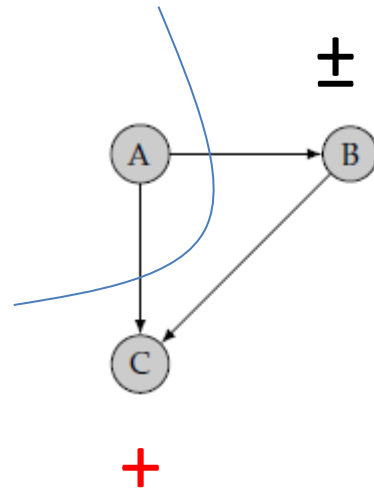
3-Put $(-)$ on all predecessor not yet marked of all vertices marked by $(-)$

4-All the vertices marked by $(\pm)$ construct an $StCC(s)$.

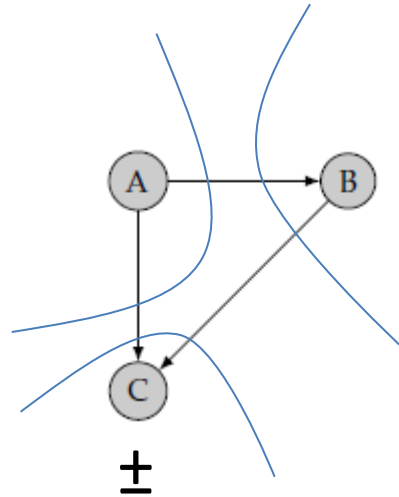
Strongly connected component



Strongly connected component



Strongly connected component



Strongly connected component

❑ CUT POINT

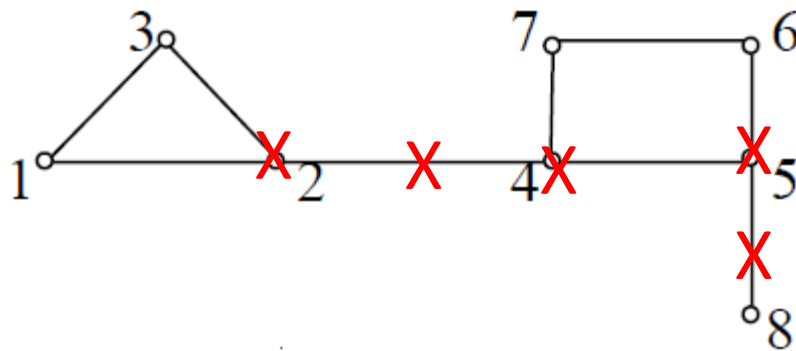
Is a vertex whose removal increases the number of connected components.

❑ BRIDGE

Is an edge whose removal increases the number of connected components.

Note: If v is a cut point of a connected graph then $G - \{v\}$ is disconnected.

Example:



2, 4, 5 are cut points.

{2, 4} and {5, 8} are bridges.

References

- 1-DIESTEL, Reinhard. *Graph theory*. Springer (print edition); Reinhard Diestel (eBooks), 2024.
- 2- Sri Chandrasekharendra Saraswathi Viswa Mahavidhyalaya, Graph theory
- 3-Introduction à la théorie des graphes
Didier Müller
- 4- Mathieu SABLIK , Graphe et langage.